## **Intersection Theory Rules Symbology**

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arxiv: 2305.01283

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#### **Canonical Differential Equation (CDE) & Symbology**



Example: Kite diagram (cut sunrise propagator)  $z_1 = l_1^2 - m^2$ ,  $z_2 = (l_2 - p)^2 - m^2$ ,  $z_3 = (l_1 - l_2)^2$ ,  $z_4 = l_2^2$ ,  $z_5 = (l_1 - p)^2$ ,  $p^2 = s$ ,

3 Master integrals:  $\varphi_1$ ,  $\varphi_2$ ,  $\varphi_3$  DE given by  $\partial_{s_i} \langle \varphi | = \Omega^{(s_i)} \langle \varphi |$ Reduction: Integration-By-Parts (IBP)  $\int d^d k \frac{\partial}{\partial k^{\mu}} q^{\mu} \frac{1}{(k^2 - m_1^2)^{\alpha_1} ((k - p_1)^2 - m_2^2)^{\alpha_2} \cdots} = 0$ 

#### **Canonical Differential Equation (CDE) & Symbology**

UT basis gives CDE:	
\n $\Omega = \varepsilon \begin{pmatrix}\n -2\log(m^2) - \log(1 - 2m^2) & 0 & 4(\log(m^2) + 2\log(1 - 2m^2) - 3\log(1 - m^2)) \\ 0 & 2\log(m^2) - 3\log(1 - 4m^2) & 6\tan^{-1}(\sqrt{4m^2 - 1})\n \end{pmatrix}$ \n	
\n        Rescale: $\Rightarrow \rightarrow 1$ \n	\n        0\n
\n $\langle \varphi_I  ^{(i+1)} = B_I^{(i+1)} + \int d\Omega_{IJ} \langle \varphi_J  ^{(i)}$ \n	
\n        Symbol: $S[W_1, W_2, \dots] \equiv \int d\log W_1 \int d\log W_2 \dots$ \n	
\n        Symbol Letter (whose complete set is known as the symbol alphabet)\n	

#### **Canonical Differential Equation (CDE)**

 $\frac{1}{4}$  eps<sup>2</sup> (G[1, {-1, 0, 1, 1, 1}] + m2 G[1, {-1, 1, 1, 1, 1}] + G[1, {0, -1, 1, 1, 1}] - G[1, {0, 0, 0, 1, 1}] - $G[1, {0, 0, 1, 0, 1}] - G[1, {0, 0, 1, 1, 0}] - G[1, {0, 0, 1, 1, 1}] + 4 m 2 G[1, {0, 0, 1, 1, 1}] + G[1, {0, 1, 0, 0, 1}]$  $G[1, {0, 1, 0, 1, 1}] - m2G[1, {0, 1, 0, 1, 1}] - G[1, {0, 1, 1, 0, 0}] - m2G[1, {0, 1, 1, 0, 1}] + G[1, {0, 1, 1, 0}]$  $m2G[1, {0, 1, 1, 1, 0}] - m2G[1, {0, 1, 1, 1}] + 3m2^{2}G[1, {0, 1, 1, 1}] + m2G[1, {1, -1, 1, 1}] +$  $\langle \varphi_1|$  $G[1, {1, 0, 0, 1, 0}] - G[1, {1, 0, 0, 1, 1}] - m2G[1, {1, 0, 0, 1, 1}] - G[1, {1, 0, 1, 0, 0}] + G[1, {1, 0, 1, 0, 1}]$  $m2G[1, {1, 0, 1, 0, 1}] - m2G[1, {1, 0, 1, 1, 0}] - m2G[1, {1, 0, 1, 1, 1}] + 3m2^{2}G[1, {1, 0, 1, 1, 1}] +$  $G[1, {1, 1, -1, 1, 1}] - G[1, {1, 1, 0, 0, 0}] - G[1, {1, 1, 0, 0, 1}] + m2G[1, {1, 1, 0, 0, 1}] - G[1, {1, 1, 0, 1, 0}] +$  $m2G[1, {1, 1, 0, 1, 0}] + G[1, {1, 1, 0, 1, 1}] - 2m2G[1, {1, 1, 0, 1, 1}] - m2^{2}G[1, {1, 1, 0, 1, 1}] + G[1, {1, 1, 1, -1, 0}] +$  $G[1, \{1, 1, 1, 0, -1\}] - G[1, \{1, 1, 1, 0, 0\}] - 2 \, m \cdot 2 \, G[1, \{1, 1, 1, 0, 0\}] + m \cdot 2 \, G[1, \{1, 1, 1, 0, 1\}] - m \cdot 2^2 \, G[1, \{1, 1, 1, 0, 1\}] +$  $m2G[1, {1, 1, 1, 1, 0}] - m2^{2}G[1, {1, 1, 1, 0}] - m2^{2}G[1, {1, 1, 1, 1, 1, 1}] + 2m2^{3}G[1, {1, 1, 1, 1, 1}]$  $\left\{\varphi_{2}\right\}$   $\frac{1}{8}\sqrt{-1+4m^{2}}\epsilon^{2}G[1, \{1, 1, 1, 0, 0\}]$   $\left\{\varphi_{3}\right\}$   $\frac{1}{4}\epsilon^{2}(\text{G}[1, \{1, 1, 1, -1, 0\}]-m^{2}\text{G}[1, \{1, 1, 1, 0, 0\}])$  $\partial_{m^2}(\varphi_1) = \sum \left[ \frac{2}{1-2m^2} - \frac{2}{m^2} (\varphi_1) + 4 \left( \frac{3}{1-m^2} + \frac{1}{m^2} - \frac{4}{1-2m^2} \right) (\varphi_3) \right]$ Reduction **Why it is so simple?**

#### **Previous Research**

Specific cases: N=4 SYM (generalized to d dim massless propagator integral), one-loop, first, second, and final entry conditions, etc (many of these methods are algebraic).

General cases: diagrammatic coaction (integration on discontinuity 1703.05064 Abreu, et. al. and its development), direct integration after expansion in the order of  $\epsilon$  (recently developed to be algebraic 2304.01776 Tan, He), etc.

#### The challenges general cases could face:

Divergence (e.g. when expanding with respect to  $\varepsilon$ )

High order of  $ε$ 

Complicated contour

Non-rational symbol (Rationalize all variables  $\rightarrow$  GPL)

…

(many of which emerge in the integration method)

#### **Our starting point**

**Challenge:** High order of  $\varepsilon \to S$ olved by CDE, iteratively giving symbols to arbitrary order of  $\varepsilon$ .

Our previous one-loop practice: Integrate the expansion of d log integrand (UT) to get CDE element (also symbol letters) 2201.12998 Chen, et al. (d log integrand gives UT 1212.5605 Nima, et al, construction in Baikov rep.see 2008.03045 & 2202.08127 Chen, et al) Observation: despite the complicated contours and trick plus distribution expansion for divergent cases the calculation could involve, letters are simply just the d log integrand take the pole values! (Roughly)



#### **Intersection number: an IBP invariant inner product**

Hypergeometric-like functions:	\n $\langle \varphi_L   \equiv \int u \varphi_L, \quad  \varphi_R \rangle \equiv \int u^{-1} \varphi_R,$ \n	Baikov rep. & Schwinger parameterization parameterization parameterization						
Intersection number:	\n $\langle \varphi_L   \varphi_R \rangle = \sum_{\mathbf{p}} \frac{\text{Res}_{\mathbf{z}=\mathbf{p}}(\psi_L \hat{\varphi}_R),$ \n	\n $\langle \varphi_L   \varphi_R \rangle = \sum_{\mathbf{p}} \frac{\text{Res}_{\mathbf{z}=\mathbf{p}}(\psi_L \hat{\varphi}_R),$ \n	\n $\langle \varphi_L   \varphi_R \rangle = \sum_{\mathbf{p}} \frac{\text{Res}_{\mathbf{z}=\mathbf{p}}(\psi_L \hat{\varphi}_R),$ \n	\n $\langle \varphi_L   \varphi_R \rangle = \sum_{\mathbf{p}} \frac{\text{Res}_{\mathbf{z}=\mathbf{p}}(\psi_L \hat{\varphi}_R),$ \n	\n $\langle \varphi_L   \varphi_R \rangle = \sum_{\mathbf{p}} \frac{\text{Res}_{\mathbf{z}=\mathbf{p}}(\psi_L \hat{\varphi}_R),$ \n	\n $\langle \varphi_L   \varphi_R \rangle = \sum_{\mathbf{p}} \frac{\text{Res}_{\mathbf{z}=\mathbf{p}}(\psi_L \hat{\varphi}_R),$ \n	\n $\langle \varphi_L   \varphi_R \rangle = \sum_{\mathbf{p}} \frac{\text{Res}_{\mathbf{z}=\mathbf{p}}(\psi_L \hat{\varphi}_R),$ \n	\n $\langle \varphi_L   \varphi_R \rangle = \frac{1810.03818 \text{ Mastrolia, Mizera}}{2002.10476 \text{ Mizera}}.$ \n
Substituting $\psi$ by Laurent series around poles (to finite order) $\rightarrow$ legal expansion needs the pole to be factorized $\rightarrow$ Section 2209.04997 <i>Chestnov, Frellesvig, Gasparotto, Mandal, Materola</i> \n\n								
Challenge: Complicated contour <								

#### **Factorization of poles**

: α denote the index of a factorized region non-ze $\mathsf{r}\mathsf{o}$  and  $i$ u-power factorized **Example (of a Degenerate pole):** Notation:  $\boldsymbol{\rho}^{(\alpha)}$   $\boldsymbol{z} \to \boldsymbol{x}^{(\alpha)}$ **p**=(0,0)  $z_1^{p_1} z_2^{p_2}(z_1)$ non-zero factorized

**Challenge:** Divergence  $\rightarrow$  addressed locally by factorization of poles and intersection theory.

People do not need to handle all poles at the same time, but only factorize one pole for each time.



#### **Intersection number**

m.

$$
\nabla_i = dz_i \wedge (\underbrace{\partial_{z_i} + \hat{\omega}_i}_{\text{only simple pole}}) \qquad \qquad \underbrace{\nabla_n \cdots \nabla_1 \psi_L}_{\text{rank } \mathbf{-1}} = \varphi_L
$$
\n
$$
\omega = \sum_i \hat{\omega}_i \, dz_i, \quad \hat{\omega}_i = \underbrace{\partial_{z_i} \log(u)}_{\text{only simple pole}} \qquad \qquad \langle \varphi_L | \varphi_R \rangle = \sum_p \underbrace{\text{Res}_{z=p}(\psi_L \hat{\varphi}_R)}_{\text{key } \mathbf{-p}}.
$$
\n
$$
\varphi^{(b)} = C^{(b)} \wedge \left[ x_i^{(\alpha)} - \rho_i^{(\alpha)} \right] \text{d} x_i^{(\alpha)}
$$
\n
$$
\text{axis only when } b_{L,i} + b_{R,i} \leq -2 \text{ for all } i
$$

#### **CDE of dlog: only first- and second-order contributions to intersection number**



 $\langle \dot{\varphi}_I | \equiv \hat{\mathrm{d}} \langle \varphi_I | = (\hat{\mathrm{d}} \Omega)_{IJ} \langle \varphi_J |$  $\left(\hat{\mathrm{d}}\Omega\right)_{IK}=\left[\left\langle\dot{\varphi}_I\right|\varphi_J\right]\left(\eta^{-1}\right)_{JK}\right]$  $\eta_{IJ} = \langle \varphi_I | \varphi_J \rangle$ 

dlog-form only involves multivariate simple pole:  $b_i > -1$ 

Non-zero contributions arise only when  $b_{L,i} + b_{R,i} \le -2$  for all i

**First-order contribution** all  $b_{L,i} + b_{R,i} = -2$ **Second-order contribution**  $b_{L,i} + b_{R,i} = -2$  except one  $b_{L,j} + b_{R,j} = -3$ 

#### **Universal formula of First- & Second-order contribution**

**Directly solving**

\n
$$
\psi \nabla_n \cdots \nabla_1 \psi_L = \varphi_L \quad \varphi^{(b)} = C^{(b)} \bigwedge_i \left[ x_i^{(\alpha)} - \rho_i^{(\alpha)} \right]^{b_i} \mathrm{d}x_i^{(\alpha)}
$$
\n**First-order contribution**

\n
$$
\underbrace{C_L^{(b_L)} C_R^{(b_R)}}_{\tilde{\gamma}_1^{(\alpha)} \cdots \tilde{\gamma}_n^{(\alpha)}} \qquad \tilde{\gamma}_i^{(\alpha)} = \gamma_i^{(\alpha)} - b_{R,i} - 1
$$
\n**Matrix**

\n
$$
\widetilde{\gamma}_1^{(\alpha)} \cdots \widetilde{\gamma}_n^{(\alpha)}
$$

**Second-order contribution**  
\n
$$
b_{L,i} + b_{R,i} = -2 \qquad -\frac{C_L^{(b_L)} C_R^{(b_R)}}{\tilde{\gamma}_1^{(\alpha)} \cdots \tilde{\gamma}_n^{(\alpha)}} \partial_{\rho_j^{(\alpha)}} \log \left( \bar{u}_{\alpha}(\boldsymbol{\rho}^{(\alpha)}) \right)
$$
\n
$$
b_{L,j} + b_{R,j} = -3 \quad \text{for one j}
$$

**Challenge:** Complicated contour  $\rightarrow \rightarrow$ **Challenge:** Non-rational symbol  $\rightarrow \rightarrow$ 

Algebraically. Simple and universal formula.



#### **(n-1)- and n-SP contribution**

$$
(\hat{d}\Omega)_{IK} = (\varphi_I|\varphi_J) (\eta^{-1})_{JK}
$$
\n
$$
\underbrace{(\hat{n}-1)\text{-variable Simple Pole}}_{(n-1)\text{-variable Simple Pole}} \xrightarrow{(\hat{n}-1)\text{-SP}} \mathbf{x}_{\underline{k}}^{(\alpha)} \qquad \underbrace{(\hat{n}^{\text{q and }\varphi_J \text{ share a}}_{n\text{-variable Simple Pole}} \text{ in--SP}} \mathbf{x}^{(\alpha)} \qquad \qquad \text{if } \hat{n} \text{ is a single pole} \qquad \text{if } \hat{n} \
$$

We will discuss why it always is a simple dlog-form in the reduced univariate problem later

 $(\text{n-1})$ -SP  $\boldsymbol{x}_{\hat{i}}^{(\alpha)}$   $\boldsymbol{\varphi}_I$  and  $\boldsymbol{\varphi}_J$  share a  $\boldsymbol{\varphi}_I$   $\boldsymbol{\varphi}_I$  and  $\boldsymbol{\varphi}_J$  share a  $\boldsymbol{\varphi}_I$   $\boldsymbol{\varphi}_I$ n-SP  $\bm{x}^{(\alpha)}$ n-variable Simple Pole

$$
b_I = b_J = -1
$$

For pure parameter factor  $P_0^{\beta_0}$ 

 $\partial_{P_0}$ first-order contribution

$$
\frac{C_I^{(-1)}C_J^{(-1)}}{\gamma^{(\alpha)}} \hat{\mathrm{d}} \log\left(\bar{u}_\alpha(\pmb{\rho}^{(\alpha)})\right)
$$

## **n-SP** chain and non-zero  $\eta_{JK}^{-1}$

$$
(\hat{d}\Omega)_{IK} = \langle \dot{\varphi}_I | \varphi_J \rangle \left( \eta^{-1} \right)_{JK} \quad \eta_{IJ} = \langle \varphi_I | \varphi_J \rangle
$$

Only when  $\varphi_I$  and  $\varphi_I$  share a n-SP,  $\eta_{II}$  could be non-zero.

n-SP chain: If  $\varphi$ <sub>I</sub> and  $\varphi$ <sub>I</sub> share an n-SP, we say that they are n-SP related (denoted as φ<sub>I</sub>~φ<sub>J</sub>) and belong to a n-SP chain. If  $\phi$ <sub>J</sub>~φ<sub>K</sub> and φ<sub>I</sub>~φ<sub>J</sub>, the three n-forms belong to an n-SP chain. Similar for more dlog-forms.



#### **CDE Selection Rules**





#### **Reduce to univariate problem**



Which can be easily analyzed systematically!

#### **Rational-type univariate problem**

$$
u = P_0^{\beta_0} (z - c_1)^{\beta_1} (z - c_2)^{\beta_2} (z - c_3)^{\beta_3}
$$

$$
\frac{1}{\partial P_0} \qquad \frac{1}{\rho_i^{(\alpha)}}
$$

 $c_{\alpha} \in \{c_1, c_2, c_3, \infty\},\$ 

 $\gamma^{(\alpha)} \in \left\{\beta_1, \beta_2, \beta_3, -\sum_i \beta_i\right\}$ 

Although the parameters here could involve the same original parameters, they are regarded as independent when we use a partial operator for each selected  $x_i^{(\alpha)}$ .

dlog integrand:  $\varphi_I$ 

$$
\in \left\{ \frac{\mathrm{d}z}{z - c_1}, \, \frac{\mathrm{d}z}{z - c_2} \right\}
$$

 $\eta = \left( \begin{matrix} \frac{1}{\gamma^{(1)}}+\frac{1}{\gamma^{(4)}} & \frac{1}{\gamma^{(4)}} \\ \frac{1}{\gamma^{(4)}} & \frac{1}{\gamma^{(2)}}+\frac{1}{\gamma^{(4)}} \end{matrix} \right)$ 

Each  $\varphi_I$  involves two poles,  $c_I$  and  $c_4 = \infty$ .

$$
\langle \dot{\varphi}_I | \varphi_I \rangle = \sum_{\alpha \neq I} \frac{\gamma^{(\alpha)}}{\gamma^{(I)}} \hat{d} \log(c_I - c_\alpha) + \eta_{II} \beta_0 \hat{d} \log P_0
$$

$$
\langle \dot{\varphi}_I | \varphi_J \rangle = -\hat{d} \log(c_I - c_J) + \eta_{IJ} \beta_0 \hat{d} \log P_0
$$

#### **All letters are pole distance and pure parameter factor!**

#### **Sqrt-type univariate problem**

Challenge:

$$
u = (z - c_1)^{\beta_1} (z - c_2)^{\beta_2} (z - c_+)^{\beta_3} (z - c_-)^{\beta_4}
$$
  
\n
$$
c_{\alpha} \in \{c_1, c_2, \infty, c_+, c_-\},
$$
  
\ndlog integrand  
\n
$$
\gamma^{(\alpha)} \in \left\{\beta_1, \beta_2, -\sum_i \beta_i, \beta_3, \beta_4\right\}
$$
  
\ndlog $\tau[z, c_1; c_+]$ , dlog $\tau[z, c_2; c_+]$ , dlog $\tau[z, \infty; c_+]$   
\n
$$
\langle \varphi_I | \varphi_I \rangle = \frac{1}{\gamma^{(I)}} \hat{d} \log(\bar{u}_I(c_I)) - \hat{d} \log(c_+ - c_-)
$$
  
\n
$$
+ \hat{d} \log(c_I - c_+) + \hat{d} \log(c_I - c_-),
$$
  
\n
$$
\langle \varphi_I | \varphi_J \rangle = \langle \varphi_J | \varphi_I \rangle = -\hat{d} \log \underline{\tau[c_I, c_J; c_+]}.
$$

By univariate rationalization, all conclusions of rational-type apply!

Non-rational symbol  $\rightarrow$   $\rightarrow$   $\rightarrow$  By merely univariate rationalization

 $\rightarrow$  Letters are pole distance and parameter factors



#### **2-loop pedagogical example**



**Example:** degenerate pole  $(\infty, 0)$   $z_A = 1/t_A$ 

$$
= t_4^{2\epsilon - \delta_1} z_5^{\delta_2} \mathcal{G}_{\infty 0}^{-\epsilon}
$$
  

$$
= t_4^{2\epsilon - \delta_1} z_5^{\delta_2} \mathcal{G}_{\infty 0}^{-\epsilon}
$$
  

$$
\mathcal{G}_{\infty 0} \equiv t_4^2 \mathcal{G}(1/t_4, z_5) \equiv t_4[r_+(t_4) - z_5][z_5 - r_-(t_4))]
$$
  
Another factor can provide a pole at (∞,0)  $z_5 - m^2(m^2 - s)t_4 + \mathcal{O}(t_4^2)$ 

 $\rightarrow$ degenerate pole

 $\rho^{(5)}$  in degenerate pole  $(\infty, 0)$ 

#### Denote 3 factorized regions at  $(\infty,0)$  as



#### **Newton polytope**



Facet  $\circled{3}$  is a degenerate facet for  $(\infty,0)$ . (The normal vector points towards the fourth quadrant.) FIG. 1. The Newton polytope of  $\mathcal{G}_{\infty 0}$ . Horizontal and vertical

Letters are related to the coefficient of the vertices!

axis are the power of  $t_4$  and  $z_5$ . The solid line represents the zero facet of  $(\infty, 0)$ .

#### **Factorization in Newton polytope**



 $\Omega_{13}$ 

$$
\left(\hat{\mathrm{d}}\Omega\right)_{IK} = \left\langle \dot{\varphi}_I | \varphi_J \right\rangle \left(\eta^{-1}\right)_{JK}
$$

$$
\left(\eta^{-1}\right)_{JK} = \begin{pmatrix} \frac{\delta_1 \delta_2(-\delta_1 - \delta_2 + \epsilon)}{6} & 0 & -2\delta_1 \delta_2 & -2\delta_1 \delta_2 \\ 0 & \epsilon^2 & 0 & 0 \\ -2\delta_1 \delta_2 & 0 & -2\epsilon (\delta_2 + \epsilon) & -\epsilon (\delta_1 + \delta_2 + \epsilon) \\ -2\delta_1 \delta_2 & 0 & \epsilon (\delta_1 + \delta_2 + \epsilon) & -2\epsilon (\delta_1 + \epsilon) \end{pmatrix}
$$

 $\langle \dot{\varphi}_1 | \varphi_1 \rangle$   $\langle \dot{\varphi}_1 | \varphi_3 \rangle$   $\langle \dot{\varphi}_1 | \varphi_4 \rangle$  need to be considered.

#### **Newton polytopes related to** Ω



 $\Omega_{13}$ 

$$
\mathcal{G} = -2m^6 + m^4(s + z_4 + z_5) + m^2(2z_4z_5 - sz_4 - sz_5) + z_4z_5(s - z_4 - z_5)
$$



For general cases, one Newton polytope will be not enough.

For sqrt-type, we also can read a part of the information of the letters for the coefficient of vertices.



#### **Summary: how we handle the challenges in general cases**

**Challenge:** High order of  $\varepsilon \to$  Solved by CDE, iteratively giving symbols to arbitrary order of  $\varepsilon$ .<br> **Challenge:** Divergence  $\to$  Addressed locally by factorization of poles and intersection theory.

**Challenge:** Complicated contour  $\rightarrow$  Algebraic formulas in intersection theory.

**Challenge:** Non-rational symbol  $\rightarrow$  Intersection theory, n-1 variables residue  $\rightarrow$  univariate

Intersection theory plays an essential role to transform the geometric integration contour problem into an algebraic problem

#### **Summary**

- With only universal formula for the first- and second-contribution of intersection number, CDE selection rules and the formula for n-SP and (n-1)-SP are derived. We show how CDE emerges for dlog integrand.
- This problem can be transformed into a univariate problem, then all letters are pole distance or parameter factor after merely univariate rationalization.
- We take a first glance at applying Newton polytope which can help people get a geometric and intuitive view of this problem.
- Since CDE also are reduction relations, intersection theory shows its true power to explicitly relate the algebraic structure of reduction and the analytic structure of Feynman integral together!

#### **Outlook**

$$
u=z_4^{\delta_1}z_5^{\delta_2}[{\cal G}(z_4,z_5)]^{-\epsilon}
$$

#### **For the reduction aspect**:

- CDE are also reduction relations. The reduction relation we get keeps the power of the propagator as a parameter, so it may serve as iterative reduction relation by taking different values of the powers.
- People can investigate elliptic (and beyond) cases.
- The formula beyond first- and second-order contribution to intersection number can be investigated. People could consider avoiding redundant calculations in intersection numbers since they may have the same formula.

#### **For the symbology aspect**:

- The role of Newton polytope can be investigated systematically.
- How to read out the symbol alphabet before the construction of dlog integrand could be considered.
- With the development of elliptic UT integrand (such as using the period matrix), elliptic symbology could be analyzed in a similar way.

# Thank you for listening



#### **dlog form of master integrals**

$$
\varphi_1 = d \log(z_4) \wedge d \log(z_5)
$$
  
\n
$$
\varphi_2 = d \log(\tau[z_4, m^2; r_{1;\pm}]) \wedge d \log \left( \frac{z_5 - r_{5+}}{z_5 - r_{5-}} \right)
$$
  
\n
$$
\varphi_3 = -d \log(\tau[z_4, \infty; r_{1;\pm}]) \wedge d \log \left( \frac{z_5 - r_{5+}}{z_5 - r_{5-}} \right),
$$
  
\n
$$
\varphi_4 = -d \log(\tau[z_5, \infty; r_{1;\pm}]) \wedge d \log \left( \frac{z_4 - r_{4+}}{z_4 - r_{4-}} \right),
$$
  
\n
$$
r_{1;\pm} \equiv r_{\pm}[\mathcal{G}_1; z_5], \qquad \mathcal{G}_1(z_5) \equiv G(l_1, p)
$$
  
\n
$$
r_{4\pm}(z_5) \equiv r_{\pm}[\mathcal{G}; z_4], \quad r_{5\pm}(z_4) \equiv r_{\pm}[\mathcal{G}; z_5],
$$
  
\n
$$
r_{5+}(\infty) = \infty, \quad r_{5-}(\infty) = 0, \quad r_{5\pm}(m^2) = m^2.
$$

#### **Details in** Ω

 $\eta_{3i}$  contribute to  $\Omega_{13}$  implies we only need to consider  $\langle \hat{d}1|1\rangle$ ,  $\langle \hat{d}1|3\rangle$  and  $\langle \hat{d}1|4\rangle$ . And due to the symmetry,  $\langle \hat{d}1|4 \rangle$  is just exchange the  $\delta_1$  and  $\delta_2$  in  $\langle \hat{d}1|3 \rangle$ . The independent nonzero contributions for  $\langle \hat{d}1|1 \rangle$  are: The N-SP  $\rho^{(1)}$  between  $\varphi_1$  itself:

$$
-\frac{\epsilon}{\delta_1 \delta_2} \left(2 \log(m^2) + \log(s - 2m^2)\right); \tag{65}
$$

The N-SP  $\rho^{(5)}$  of  $\varphi_1$  itself:

$$
-\frac{\epsilon}{(\epsilon - \delta_1 + \delta_2)\delta_2} \left(\log(m^2) + \log(s - m^2)\right); \qquad (66)
$$

The N-SP  $\rho^{(8)}$  of  $\varphi_1$  itself are given by exchange symmetry.

For  $\langle \hat{d}1|3 \rangle$ , the (N-1)-SP between  $\rho_2^{(5)}$  of  $\varphi_1$  and  $\varphi_3$ gives

$$
\frac{1}{\epsilon - \delta_1 + \delta_2} \left( \log(m^2) + \log(s - m^2) \right). \tag{67}
$$

The contribution of shared (N-1)-SP  $\rho_1^{(8)}$  between  $\varphi_1$  and  $\varphi_4$  for  $\langle d_1 | 4 \rangle$  are given by exchange symmetry.

Some contributions from  $N$ -SP and  $(N-1)$ -SP are  $\hat{d} \log(C)$  and equals 0, so they are not shown in the above. Combining  $\langle \hat{d}1|i\rangle$  and  $\eta_{i3}^{-1}$ , take  $\delta_1 = \delta_2$ , add the symmetry that  $\langle \varphi_3 | = \langle \varphi_4 |$  when  $\delta_1 = \delta_2$  (now there are only 3 master integrals), and take a rescale transformation  $s \to 1$  we get the final result of  $\Omega_{13}$  to be

$$
4\epsilon (2\log(1-2m^2) - 3\log(1-m^2) + \log(m^2)) \qquad (68)
$$

Notice that we haven't taken  $\delta_i$  to be zero, so we can check this result by comparing it to the differential equations obtained from traditional IBP with the same dlog basis with different choice of  $\delta_i$  (for example  $\delta_1 = \delta_2 = 0$ ) or  $\delta_1 = \delta_2 = 1$  or some other positive integers), and we find our result is right.