BOOTSTRAPPING THE BFSS MODEL

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• Matrix Quantum Mechanics. (In progress, with Henry Lin)



[Anderson and Kruczenski, 2017] [Lin. 2020] [Han et al., 2020] [Kazakov and Zheng, 2022] [Kazakov and Zheng, 2023] [Cho et al., 2022] [Lin, 2023] [Kazakov and Zheng, 2024] [Li and Zhou, 2024]

Basically bootstrap method is solving problems in theoretical physics by optimization theory.

· Quadratic programming:

min y
s.t.
$$y = x^2 + 3x + 1$$
 (1)

· Linear programming:

$$\begin{array}{rcl} \max & 300x + 100y \\ \text{s.t.} & 6x + 3y &\leq 40 \\ & x - 3y &\leq 0 \\ & x + \frac{1}{4}y &\leq 4 \end{array} \tag{2}$$

· Semi-definite Programming:

min
$$2x + 3y$$

s.t. $\begin{pmatrix} x & 1 \\ 1 & y \end{pmatrix} \succeq 0$ (3)

- Linear programming and Quadratic programming are special situations of Semi-definite Programming(SDP).
- $\cdot\,$ They all fall into the class of Convex Optimization.
- Generally we cannot solve large-scale non-convex optimization problem (NP hard).

The Hamiltonian is chosen to be [Banks, Fischler, Shenker, Susskind 97]:

$$H = \frac{1}{2} \operatorname{Tr} \left(g^2 P_l^2 - \frac{1}{2g^2} \left[X_l, X_j \right]^2 - \psi_\alpha \gamma_{\alpha\beta}^l \left[X_l, \psi_\beta \right] \right)$$
(4)

Here:

$$[X_{ij}, P_{kl}] = i\delta_{il}\delta_{jk}, \{\psi_{\alpha,ij}, \psi_{\beta,kl}\} = \delta_{\alpha\beta}\delta_{il}\delta_{kj}$$
(5)

Dual to the dynamics of the D0-brane.

The matrices are in multiples of the *SO*(9) symmetry, with the supercharge:

$$Q_{\alpha} = g \operatorname{tr} P_{I} \gamma_{\alpha\beta}^{I} \psi_{\beta} - \frac{i}{2g} \operatorname{tr} [X^{I}, X^{J}] \gamma_{\alpha\beta}^{IJ} \psi_{\beta}$$
(6)

- $\cdot\,$ physics simplifies at large N but the computation gets harder
- $\cdot\,$ sign problem, finite volume truncation, finite N truncation

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診质生产力

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Bootstrap:

- · works in large N directly; gives rigorous bounds
- $\cdot\,$ no sign problem, no finite volunmn or finite N truncation

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Bootstrap:

- · works in large N directly; gives rigorous bounds
- \cdot no sign problem, no finite volunmn or finite N truncation $extsf{^4}$



The Hamiltonian is chosen to be(g = 1):

$$H = \frac{1}{2}(p_x^2 + p_y^2) + \frac{1}{2}gx^2y^2$$
(7)

This model is not trivially solved by numerical method/analytical method[Hoppe, 1980] [Simon, 1983][Komatsu et al., 2024]. It keeps certain key feature of the BFSS Hamiltonian:

$$H = \frac{1}{2} \operatorname{Tr} \left(g^2 P_l^2 - \frac{1}{2g^2} \left[X_l, X_j \right]^2 - \psi_\alpha \gamma_{\alpha\beta}^l \left[X_l, \psi_\beta \right] \right)$$
(8)

Our goal is to solve all the eigenvalues and all the expectations of the operators under different eigenstates.

For an eigenstate with eigenvalue *E*, the corresponding loop equations are:

$$\langle [H, \mathcal{O}] \rangle = 0, \,\forall \mathcal{O} \tag{9}$$

$$\langle H\mathcal{O} \rangle = E \langle \mathcal{O} \rangle, \, \forall \mathcal{O}$$
 (10)

together with the Ward identities:

$$\langle \mathcal{O}_g \rangle = \langle \mathcal{O} \rangle, \, \forall \mathcal{O}$$
 (11)

These are all linear equations, we can expand any operators as:

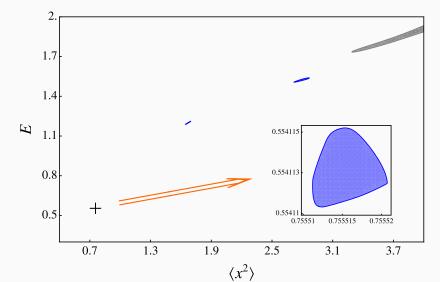
$$\mathcal{O} = \sum \alpha_{mnts} p_x^m p_y^n x^t y^s \tag{12}$$

Generalization: Any inner products defined on the vector space of operators or its subspace could leads to positivity condition:

$$\langle \mathcal{O} | \mathcal{O} \rangle = \langle \mathcal{O}^{\dagger} \mathcal{O} \rangle = \alpha^{*T} \mathcal{M} \alpha \ge 0, \, \forall \alpha \Leftrightarrow \mathcal{M} \succeq 0.$$
(13)

Here we do the expansion $\mathcal{O} = \sum \alpha_i \mathcal{O}_i, \ \mathcal{M}_{ij} = \langle \mathcal{O}_i^{\dagger} \mathcal{O}_j \rangle.$

Toy model($\Lambda = 12$)



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For the ground state, or more generally, any stationary state, the corresponding positivities are:

$$\langle \mathcal{O}^{\dagger} \mathcal{O} \rangle \ge 0, \, \forall \mathcal{O}$$
 (14)

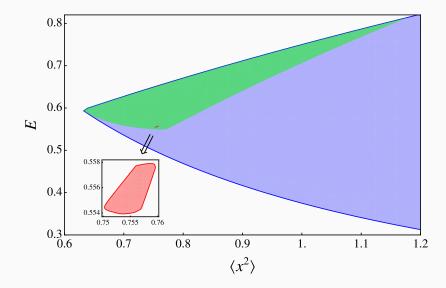
$$\langle \mathcal{O}^{\dagger}[H, \mathcal{O}] \rangle \ge 0, \, \forall \mathcal{O}$$
 (15)

The later positivity is specialized for the ground state. For more general thermal state with inverse temperature β [Fawzi, Fawzi and Scalet 23],

$$\langle \mathcal{O}^{\dagger} \mathcal{O} \rangle \log \frac{\langle \mathcal{O}^{\dagger} \mathcal{O} \rangle}{\langle \mathcal{O} \mathcal{O}^{\dagger} \rangle} \leq \beta \langle \mathcal{O}^{\dagger} [H, \mathcal{O}] \rangle, \, \forall \mathcal{O}$$
 (16)

Mathematically, these positivities together with the loop equations is necessary and sufficient.

GROUND STATE $(\Lambda = 4, 6, 8)$



The Hamiltonian is chosen to be:

$$H = tr(P^2 + X^2 + gX^4)$$
(17)

Here X is a large N Hermitian matrix:

$$[X_{ij}, P_{kl}] = i\delta_{il}\delta_{jk} \tag{18}$$

The ground state is known to be solvable. [Han et al., 2020] [WIP w/ Henry Lin] The corresponding loop equations are:

$$\langle [H, \mathcal{O}] \rangle = 0, \,\forall \mathcal{O} \tag{19}$$

$$\langle \operatorname{tr}(G\mathcal{O}) \rangle = 0, \, \forall \mathcal{O}$$
 (20)

together with the cyclicity of trO. G = i[X, P] + I is the generator of the SU(N) gauge symmetry.

Result: general words in *P* and *X* can be reduced to polynomials of trX^m .

$$trP^{2}X^{2}P^{2}X^{4} = \frac{12}{77}g^{2}trX^{14} - \frac{2}{3}gtrX^{2}trX^{6} - \frac{1}{5}gtrX^{8} + \frac{40}{231}gtrX^{12} + \frac{trX^{2}}{24} - \frac{1}{3}trX^{2}trX^{4} - \frac{trX^{6}}{10} + \frac{trX^{10}}{21}$$
(21)

For the ground state, or more generally, any stationary state, the corresponding loop equations are:

$$\langle \mathcal{O}^{\dagger} \mathcal{O} \rangle \ge 0, \, \forall \mathcal{O}$$
 (22)

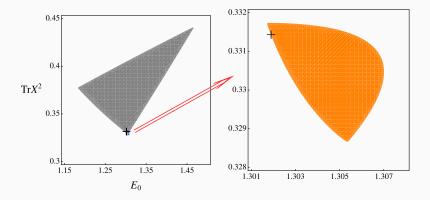
$$\langle \mathcal{O}^{\dagger}[H, \mathcal{O}] \rangle \ge 0, \, \forall \mathcal{O}$$
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The later positivity is specialized for the ground state. For more general thermal state with inverse temperature β [Fawzi, Fawzi and Scalet 23],

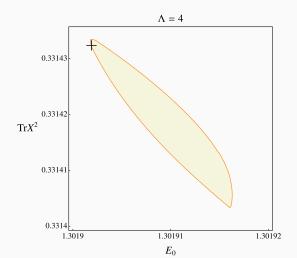
$$\langle \mathcal{O}^{\dagger} \mathcal{O} \rangle \log \frac{\langle \mathcal{O}^{\dagger} \mathcal{O} \rangle}{\langle \mathcal{O} \mathcal{O}^{\dagger} \rangle} \leq \beta \langle \mathcal{O}^{\dagger} [H, \mathcal{O}] \rangle, \, \forall \mathcal{O}$$
 (24)

Mathematically, these positivities together with the loop equations is necessary and sufficient.

The illustration of convergence, the left one is $\Lambda = 2$, whereas the right one corresponds to $\Lambda = 3$. The size of the SDP matrix is 2, 2, 2 and 3, 3, 2, 3, respectively,



The size of the SDP matrices are 5, 4, 4, 4.



The Hamiltonian is chosen to be [Banks, Fischler, Shenker, Susskind 97]:

$$H = \frac{1}{2} \operatorname{Tr} \left(g^2 P_l^2 - \frac{1}{2g^2} \left[X_l, X_j \right]^2 - \psi_\alpha \gamma_{\alpha\beta}^l \left[X_l, \psi_\beta \right] \right)$$
(25)

Here:

$$[X_{ij}, P_{kl}] = i\delta_{il}\delta_{jk}, \{\psi_{\alpha,ij}, \psi_{\beta,kl}\} = \delta_{\alpha\beta}\delta_{il}\delta_{kj}$$
(26)

Dual to the dynamics of the D0-brane.

The matrices are in multiples of the *SO*(9) symmetry, with the supercharge:

$$Q_{\alpha} = g \operatorname{tr} P_{I} \gamma_{\alpha\beta}^{I} \psi_{\beta} - \frac{i}{2g} \operatorname{tr} [X^{I}, X^{J}] \gamma_{\alpha\beta}^{IJ} \psi_{\beta}$$
(27)

Loop equations:

$$\langle [H, \mathcal{O}] \rangle = 0$$
 (28)

$$\langle \{Q_{\alpha}, \mathcal{O}_{\alpha}\} \rangle = 0 \tag{29}$$

$$\langle \mathcal{O}_1 \mathcal{O}_2 \rangle = \langle \mathcal{O}_2 \mathcal{O}_1 \rangle - \langle [\mathcal{O}_1, \mathcal{O}_2] \rangle$$
 (30)

$$\langle \operatorname{tr}(C_{ij}\mathcal{O}_{ji}) \rangle = 0, \, \forall \mathcal{O}$$
 (31)

This is the gauge singlet condition:

$$C_{ij} = -[X', P']_{ij} - \psi^{\alpha}_{ik} \psi^{\alpha}_{kj} - \mathbf{1}_{ij}$$
(32)

Positivities:

$$\langle \mathcal{O}^{\dagger} \mathcal{O} \rangle \ge 0, \, \forall \mathcal{O}$$
 (33)

 $\langle \mathcal{O}^{\dagger}[H, \mathcal{O}] \rangle \ge 0, \, \forall \mathcal{O}$ (34)

Loop equations:

$$\langle [\underline{H}, \underline{O}] \rangle = 0 \tag{35}$$

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 (38)

This is the gauge singlet condition:

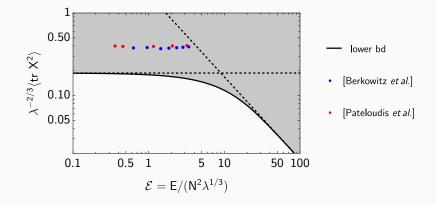
$$C_{ij} = -[X^{\prime}, P^{\prime}]_{ij} - \psi^{\alpha}_{ik}\psi^{\alpha}_{kj} - \mathbf{1}_{ij}$$
(39)

Positivities:

$$\langle \mathcal{O}^{\dagger} \mathcal{O} \rangle \ge 0, \, \forall \mathcal{O}$$
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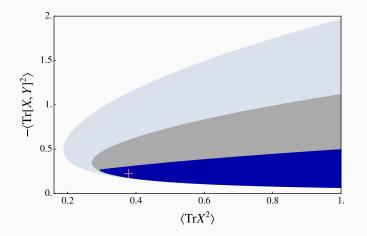
 $\underline{\langle \mathcal{O}^{\dagger}[\mathcal{H},\mathcal{O}]\rangle \geq 0}, \forall \mathcal{O}$ (41)

NUMERICAL RESULT



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Pink cross + is the Monte Carlo result of [Pateloudis et al, 22].

Records	$\langle tr X^2 \rangle$
MC [Pateloudis et al, 2022]	~ 0.37
Primitive bootstrap[Lin, 2023]	≥ 0.1875
cutoff 6	≥ 0.294
cutoff 7	≥ 0.331

Even at level 7, the SDP problem scale is extremely small (at most 10×10 matrix). Which solves instantly on a laptop.

QUESTIONS?

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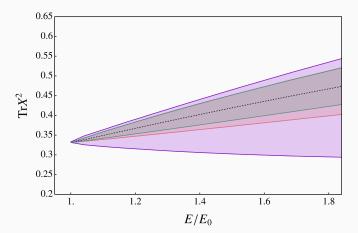
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The dashed line is the thermal state with the corresponding energy expectation. Different colors correspond to $\Lambda = 8, 18, 26$.



The partition function is chosen to be:

$$Z = \lim_{N \to \infty} Z_N = \lim_{N \to \infty} \int d^{N^2} M \, \mathrm{e}^{-N \mathrm{tr} V(M)}, \quad V(x) = \frac{1}{2} \mu x^2 + \frac{1}{4} g x^4, \quad (42)$$

The integration is over Hermitian matrix.

The basis of operators are:

$$\mathcal{W}_{k} = \langle \mathrm{Tr} M^{k} \rangle = \lim_{N \to \infty} \int \frac{d^{N^{2}} M}{Z_{N}} \frac{1}{N} \mathrm{tr} M^{k} \mathrm{e}^{-N \mathrm{tr} V(M)}.$$
(43)

And the Schwinger-Dyson equations:

$$\mu \mathcal{W}_{k+1} + g \mathcal{W}_{k+3} = \sum_{l=0}^{k-1} \mathcal{W}_l \ \mathcal{W}_{k-l+1}, \ k = 1, 2, 3, \dots$$
(44)

Generalization: Any inner products defined on the vector space of operators or its subspace could leads to positivity condition:

$$\langle \mathcal{O} | \mathcal{O} \rangle = \langle \mathcal{O}^{\dagger} \mathcal{O} \rangle = \alpha^{*\mathrm{T}} \mathcal{M} \alpha \ge 0, \, \forall \alpha \Leftrightarrow \mathcal{M} \succeq 0.$$
(45)

Here we do the expansion $\mathcal{O} = \sum \alpha_i \mathcal{O}_i, \ \mathcal{M}_{ij} = \langle \mathcal{O}_i^{\dagger} \mathcal{O}_j \rangle.$

In the above case of Hermitian matrix integration, we were taking adjoint to be Hermitian conjugation:

$$\mathcal{O}^{\dagger} = \mathcal{O}^{*\mathrm{T}} = \mathcal{O} \tag{46}$$

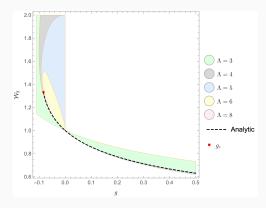
Considering the expectations of square of polynomials are always positive semi-definite:

$$\frac{1}{Z} \int_{-\infty}^{\infty} dM \operatorname{Tr}(\sum \alpha_i M^i)^2 \exp(-N \operatorname{tr} V(M)) \ge 0, \, \forall \alpha$$
(47)

This is a quadratic form in α , its positivity is equivalent to:

$$\mathbb{W} = \begin{pmatrix} \mathcal{W}_0 & \mathcal{W}_1 & \mathcal{W}_2 & \dots \\ \mathcal{W}_1 & \mathcal{W}_2 & \mathcal{W}_3 & \dots \\ \mathcal{W}_2 & \mathcal{W}_3 & \mathcal{W}_4 & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix} \succeq 0$$
(48)

This is the result of bootstrapping $\mu = 1$ and \mathbb{Z}_2 symmetry preserving solution $\mathcal{W}_1 = 0$. From the loop equation and symmetry assumption, all moments are polynomial functions of \mathcal{W}_2 .



Here we propose to study the following two-matrix model:

$$Z = \lim_{N \to \infty} \int d^{N^2} A \, d^{N^2} B \, \mathrm{e}^{-N \mathrm{tr} \left(-h[A,B]^2/2 + A^2/2 + g A^4/4 + B^2/2 + g B^4/4 \right)} \tag{49}$$

The integration is over Hermitian matrix. To the best of our knowledge, this model with general g and h value, is not solvable!

$$\begin{split} &\operatorname{Tr} A^2, \ \operatorname{Tr} A^4, \ \operatorname{Tr} A^2 B^2, \ \operatorname{Tr} ABAB, \ \operatorname{Tr} A^6, \ \operatorname{Tr} A^4 B^2, \ \operatorname{Tr} A^3 BAB, \ \operatorname{Tr} A^2 BA^2 B, \ \operatorname{Tr} A^8, \\ &\operatorname{Tr} A^6 B^2, \ \operatorname{Tr} A^5 BAB, \ \operatorname{Tr} A^4 BA^2 B, \ \operatorname{Tr} A^4 B^4, \ \operatorname{Tr} A^3 BA^3 B, \ \operatorname{Tr} A^3 BAB^3, \ \operatorname{Tr} A^3 B^2 AB^2, \\ &\operatorname{Tr} A^2 BABAB^2, \ \operatorname{Tr} A^2 BAB^2 AB, \ \operatorname{Tr} A^2 B^2 A^2 B^2, \ \operatorname{Tr} ABABABABAB \dots \end{split}$$

(50)

 $\beta = (\mathrm{Tr} A^2)^2$:

 $1 = \mathrm{Tr}A^2 + q\mathrm{Tr}A^4 - h(-2\mathrm{Tr}A^2B^2 + 2\mathrm{Tr}ABAB)$ $0 = -2\mathrm{Tr}A^2 + \mathrm{Tr}A^4 - h(2\mathrm{Tr}A^3BAB - 2\mathrm{Tr}A^4B^2) + q\mathrm{Tr}A^6$ $0 = -\mathrm{Tr}A^{2} + \mathrm{Tr}A^{2}B^{2} - h(-\mathrm{Tr}A^{2}BA^{2}B + 2\mathrm{Tr}A^{3}BAB - \mathrm{Tr}A^{4}B^{2}) + q\mathrm{Tr}A^{4}B^{2}$ $0 = -h(2\mathrm{Tr}A^{2}BA^{2}B - 2\mathrm{Tr}A^{3}BAB) + q\mathrm{Tr}A^{3}BAB + \mathrm{Tr}ABAB$ $\beta = -2\mathrm{Tr}A^4 + \mathrm{Tr}A^6 - h(2\mathrm{Tr}A^5BAB - 2\mathrm{Tr}A^6B^2) + q\mathrm{Tr}A^8$ $\beta = -\text{Tr}A^{2}B^{2} + \text{Tr}A^{4}B^{2} - h(-\text{Tr}A^{3}B^{2}AB^{2} + 2\text{Tr}A^{3}BAB^{3} - \text{Tr}A^{4}B^{4}) + q\text{Tr}A^{6}B^{2}$ $0 = -2\text{Tr}A^{2}B^{2} - h(-\text{Tr}A^{2}B^{2}A^{2}B^{2} + 2\text{Tr}A^{2}BABAB^{2} - \text{Tr}A^{3}B^{2}AB^{2}) + \text{Tr}A^{4}B^{2} + q\text{Tr}A^{6}B^{2}$ $0 = -\mathrm{Tr}A^4 + \mathrm{Tr}A^4B^2 + q\mathrm{Tr}A^4B^4 - h(-\mathrm{Tr}A^4BA^2B + 2\mathrm{Tr}A^5BAB - \mathrm{Tr}A^6B^2)$ $0 = \text{Tr}A^3BAB - h(2\text{Tr}A^2BAB^2AB - \text{Tr}A^2BABAB^2 - \text{Tr}A^3BAB^3) + q\text{Tr}A^5BAB - \text{Tr}ABAB$ $0 = TrA^{3}BAB + qTrA^{5}BAB - 2TrABAB - h(-2TrA^{2}BABAB^{2} + 2TrABABABABA)$ $0 = \mathrm{Tr}A^{3}BAB + g\mathrm{Tr}A^{3}BAB^{3} - h(-\mathrm{Tr}A^{3}BA^{3}B + 2\mathrm{Tr}A^{4}BA^{2}B - \mathrm{Tr}A^{5}BAB)$ $0 = q \operatorname{Tr} A^3 B A^3 B + \operatorname{Tr} A^3 B A B - h (2 \operatorname{Tr} A^3 B^2 A B^2 - 2 \operatorname{Tr} A^3 B A B^3)$ $0 = -\mathrm{Tr}A^{2}B^{2} + \mathrm{Tr}A^{2}BA^{2}B - h(-\mathrm{Tr}A^{2}BAB^{2}AB + 2\mathrm{Tr}A^{2}BABAB^{2} - \mathrm{Tr}A^{3}B^{2}AB^{2}) + q\mathrm{Tr}A^{4}BA^{2}B$ $\beta = \mathrm{Tr}A^2BA^2B + q\mathrm{Tr}A^3B^2AB^2 - h(2\mathrm{Tr}A^3BA^3B - 2\mathrm{Tr}A^4BA^2B).$

(51)

For example, the block for the even-odd words reads:

1	TrA^2	${\rm Tr} A^4$	$\mathrm{Tr}A^2B^2$	$\mathrm{Tr} ABAB$	$\mathrm{Tr}A^2B^2$)
	${\rm Tr} A^4$	${\rm Tr} A^6$	${\rm Tr} A^4 B^2$	$\mathrm{Tr}A^3BAB$	$\mathrm{Tr}A^4B^2$	
	$\mathrm{Tr}A^2B^2$	$\mathrm{Tr}A^4B^2$	$\mathrm{Tr}A^4B^2$	$\mathrm{Tr}A^3BAB$	$\mathrm{Tr}A^2BA^2B$	$\succeq 0$
	$\mathrm{Tr}ABAB$	$\mathrm{Tr}A^3BAB$	$\mathrm{Tr}A^3BAB$	$\mathrm{Tr}A^2BA^2B$	$\mathrm{Tr}A^{3}BAB$	
	$\mathrm{Tr}A^2B^2$	$\mathrm{Tr}A^4B^2$	$\mathrm{Tr}A^2BA^2B$	$\mathrm{Tr}A^3BAB$	TrA^4B^2)
						(52)

All the constraints are convex except the quadratic loop equations!

Our general strategy: we treat the quadratic terms in the loop equations as independent variable, and replace the algebraic equality by the convex inequality:

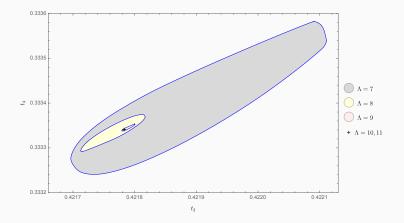
$$Q = XX^{\mathrm{T}}$$
(53)

to:

$$\mathcal{R} = \begin{pmatrix} 1 & x^{\mathrm{T}} \\ x & Q \end{pmatrix} \succeq 0.$$
 (54)

For the previous situation, we have a simple matrix:

$$\mathcal{R} = \begin{pmatrix} 1 & \mathrm{Tr}A^2 \\ \mathrm{Tr}A^2 & \beta \end{pmatrix} \succeq 0.$$
 (55)



 $\Lambda = 11, \ g = h = 1: \begin{cases} 0.421783612 \le \langle \mathrm{Tr}A^2 \rangle \le 0.421784687 \\ 0.333341358 \le \langle \mathrm{Tr}A^4 \rangle \le 0.333342131 \end{cases}$

35

(56)

Compared to the MC study of the same model 2111.02410 (Jha), we are convinced that for this model bootstrap is at least two order of magnitude more efficient than MC.

- $\cdot\,$ MC: 80-85 hours for N=800 simulation to get 4.5 digits.
- \cdot Bootstrap: less than 1 hour to get 6 digits.